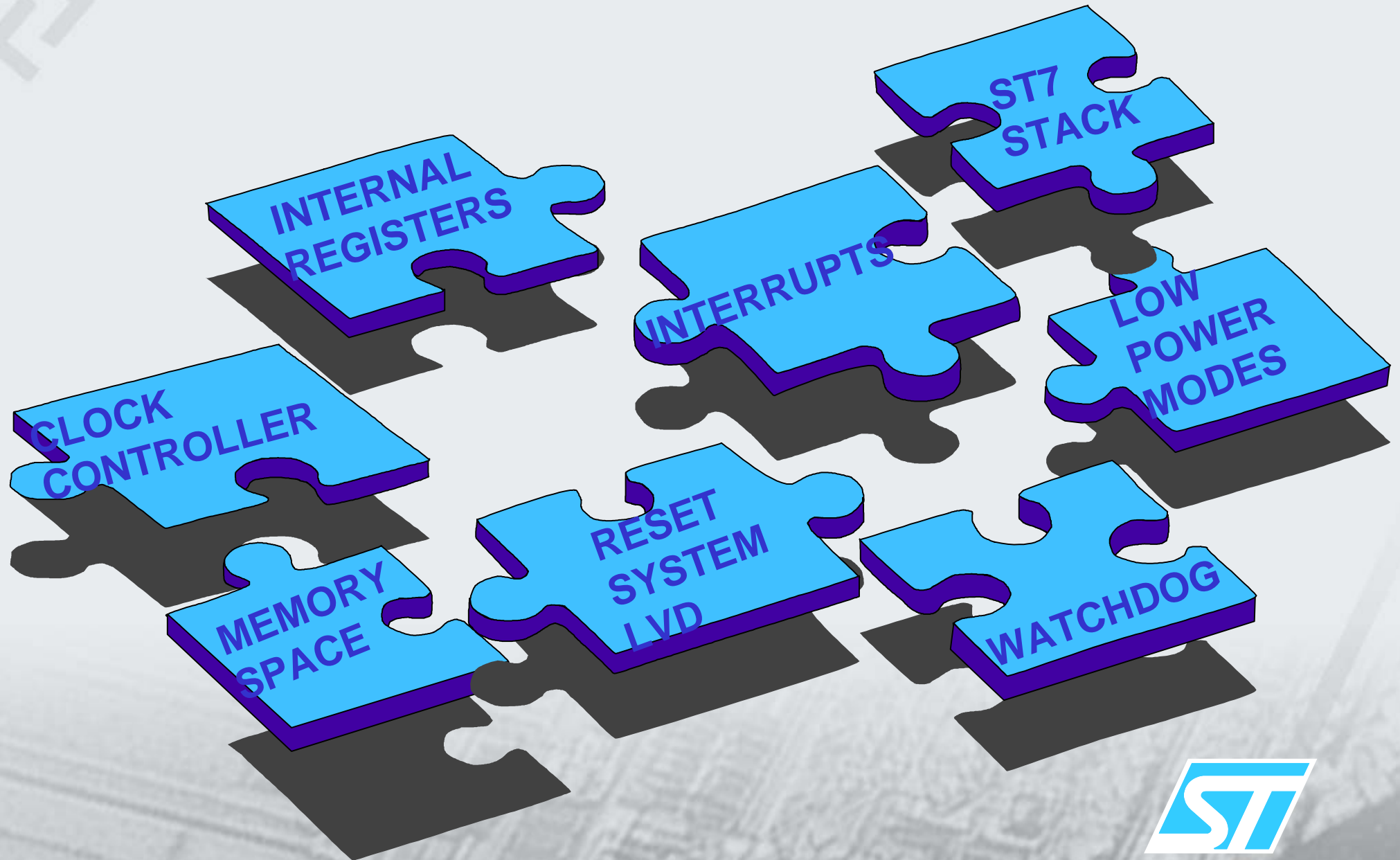


# ST7 TECHNICAL TRAINING

1. INTRODUCTION
2. CORE
3. ADDRESSING MODES
4. ASSEMBLY TOOLCHAIN
5. STVD7 DEBUGGER
6. HARDWARE TOOLS
7. PERIPHERALS
8. ST-REALIZER II
9. C TOOLCHAINS



# ST7 CORE



# ST7 CORE

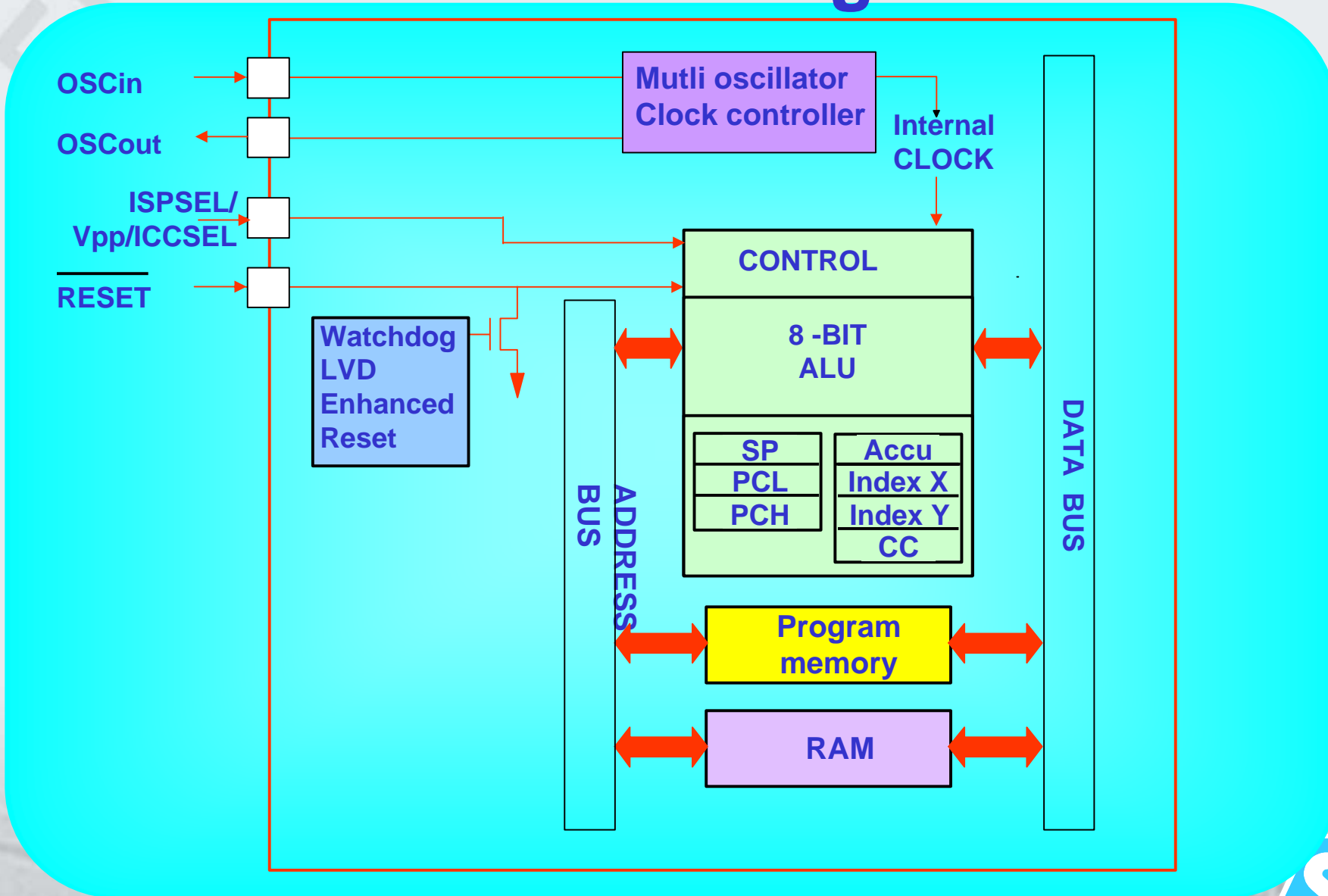
## General Description

- The ST7 core (von neuman architecture) is built around:
  - An 8-bit Arithmetic and Logic Unit (ALU)
  - 6 internal registers: Accumulator (A), X and Y index registers, Program Counter (PC), the Stack Pointer (SP) and the Code Condition register (CC)
  - A controller block
- It interfaces with:
  - An on-chip oscillator
  - A reset block
  - Address and data buses to access memories and peripherals
  - An interrupt controller



# ST7 CORE

## Block Diagram



# ST7 CORE

## Internal Registers (1)

- The ACCUMULATOR is an 8-bit general purpose register used to hold:
  - Operands
  - Results of arithmetic and logic operation
- The X and Y REGISTERS are two 8-bit registers used to:
  - Create effective addresses
  - Store temporary data



Y is not automatically stacked. If needed, it must be done using the PUSH and POP instructions  
Instructions using X are faster than the ones using Y



# ST7 CORE

## Internal Registers (2)

- The PROGRAM COUNTER PC is a 16-bit register used to store the address of the next instruction to be executed by the CPU. As a result, the ST7 can address up to 64k of program memory
- The STACK POINTER SP is a 16-bit register. The MSB is fixed by hardware
- The CODE CONDITION CC is a 5-bit register

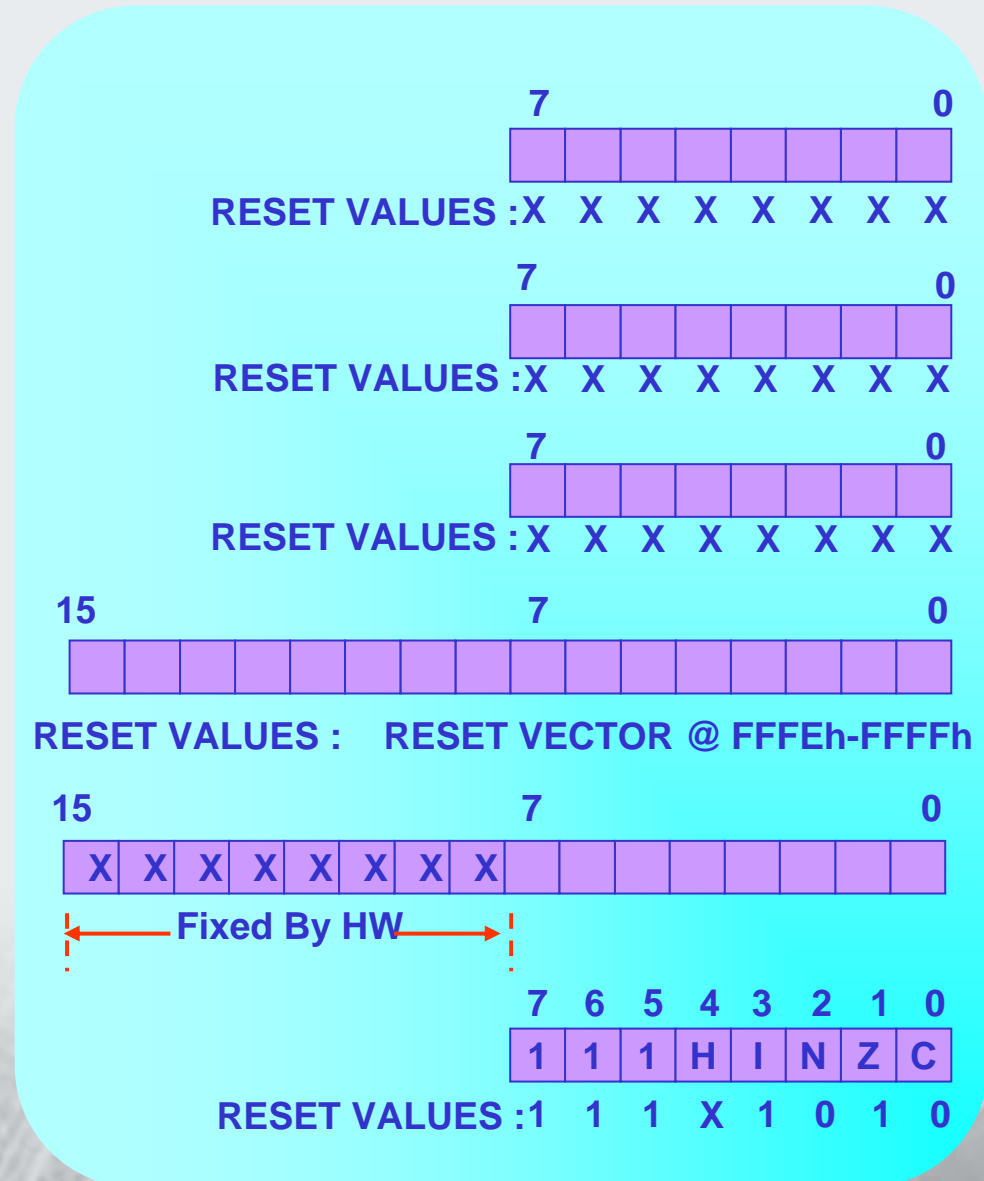
| BIT | NAME             | DESCRIPTION   |
|-----|------------------|---|
| H   | Half Carry Bit   | H=1 when a carry occurs during ADD and ADC instructions             |
| I   | Interrupt mask   | I=1 disabled the interrupt  |
| N   | Negative bit     | N=1 if the result of the last operation is negative                 |
| Z   | Zero bit         | Z=1 if the result of the last operation is zero                     |
| C   | Carry/Borrow bit | Affected when carry or borrow out occur and some inst. are executed |



# ST7 CORE

## Internal Registers (3)

- Accumulator:
- X Index register:
- Y Index register:
- Program counter:
- Stack pointer:
- Condition code register:



# ST7 CORE

## Stack manipulation (1)

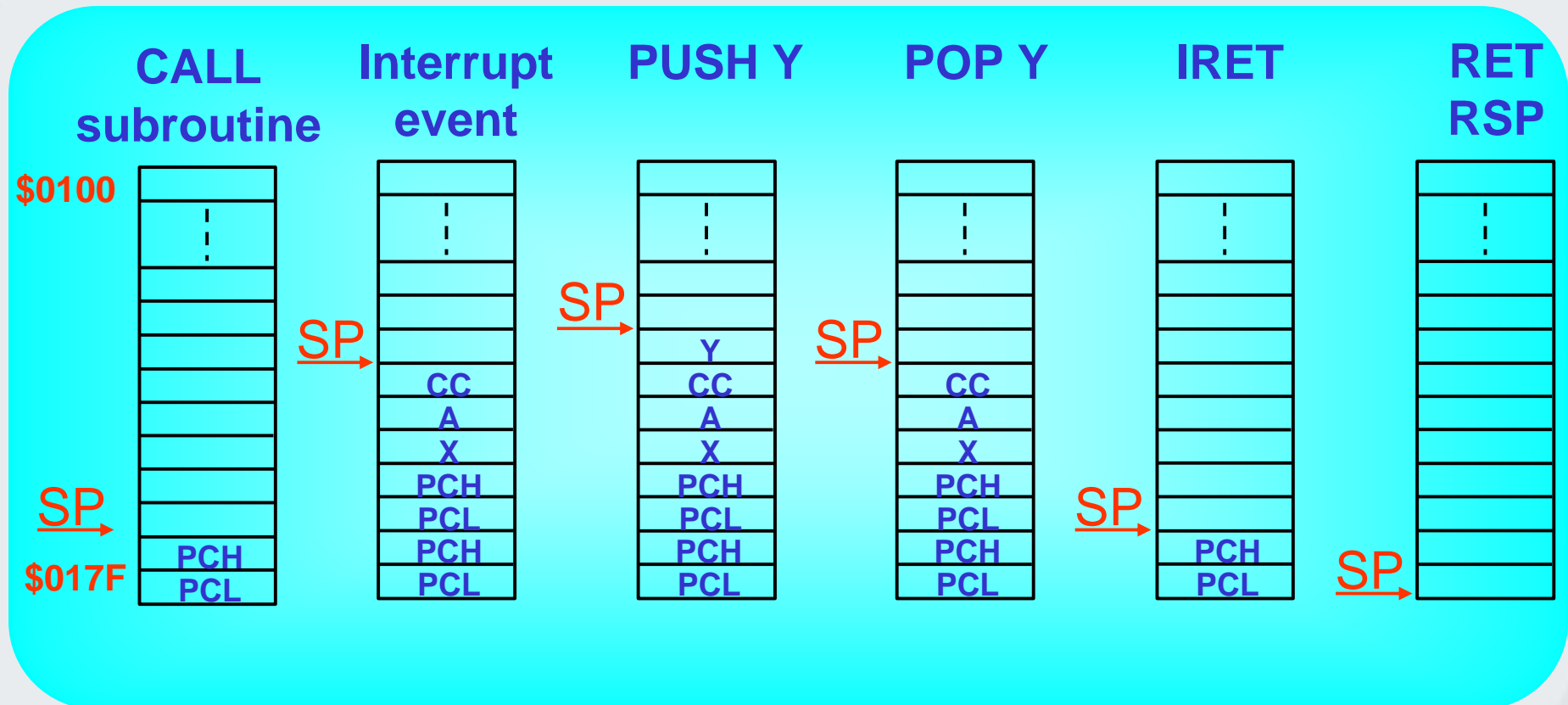
- Purpose:
  - Save the CPU context during subroutine calls or interrupts
  - Save temporary user's data (PUSH and POP instructions)
- In case of overflow (lower limit exceeded):
  - SP rolls over to the higher address
  - Value at the higher address is overwritten so lost
  - Stack overflow is not indicated





# ST7 CORE

## Stack manipulation (2)



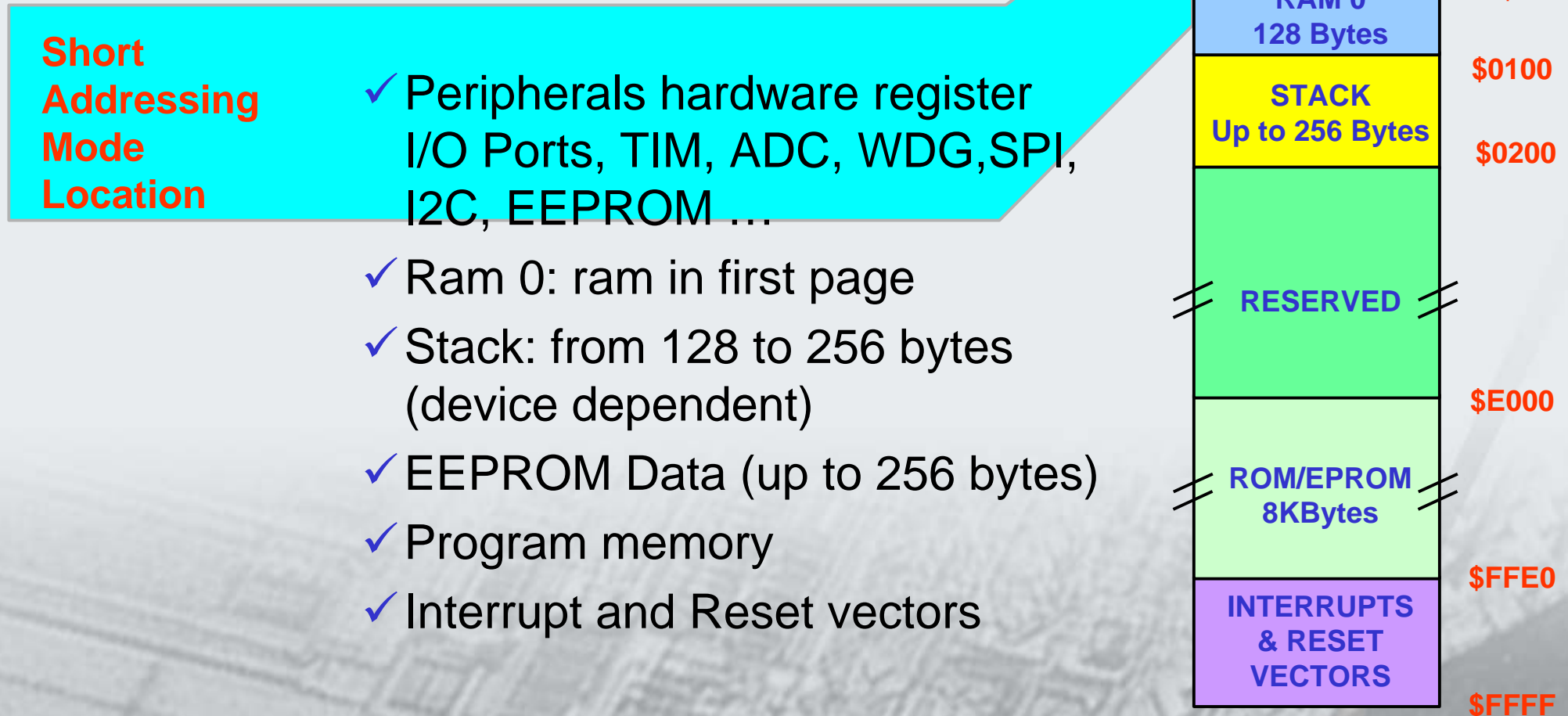
- Stack size and position is device dependent:
  - ST72254: 128 bytes (\$0100 to \$017F)
  - ST72521: 256 bytes (\$0100 to \$01FF)
  - ST7Lite0: 64 bytes (\$00C0 to \$00FF)
- Stack position can be reinitialized thanks to "ld SP, A" or reset by "RSP"



# ST7 CORE

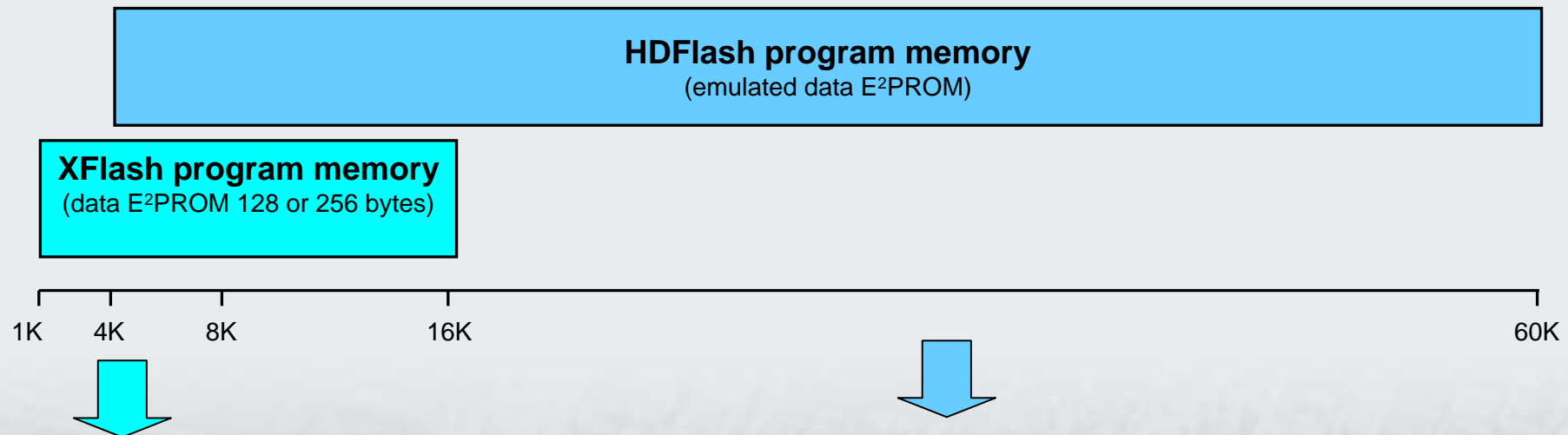
## The memory space

- The memory can be made of 6 different blocks:



# TWO FLASH TECHNOLOGIES for cost vs. feature optimization

- General features:
  - **0.5 $\mu$  technology**
  - **Very high reliability with 20 year retention**
  - **High cycling capability up to 300 K W/E**
  - **Patented high memory protection level**



## ● XFlash

- **eXtended Flash**
- **E<sup>2</sup>prom technology**

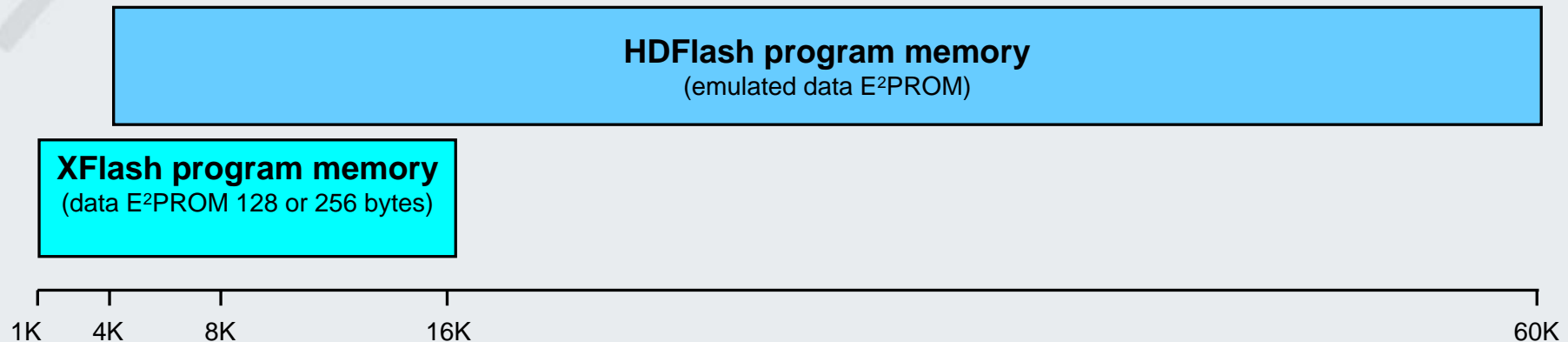
## ● HDFlash

- **High Density Flash**
- **True Flash technology**



# TWO FLASH TECHNOLOGIES

## for ST7 Product Family



- **XFlash** ST7 families
  - ST7Lite family from 1k to 8k
  - ST72F344 (16k)

- **HDFlash** ST7 families
  - ST72F52x/32x
  - ST72F56x
  - ST72F6xx
  - ST72F32x



# TWO FLASH TECHNOLOGIES

## for cost vs. feature optimization

### • XFlash

- Single voltage
- Cycling:
  - Ⓢ 10K in program memory
  - Ⓢ 300K in data e<sup>2</sup>prom
- Programming method:
  - Ⓢ Byte per byte or parallel (x32) programming with hardware control
- Prog/Erase time:
  - Ⓢ 5ms for 1 to 32Bytes (including erasing)
- Supply conditions
  - Ⓢ  $2.4V \leq V_{DD} \leq 5.5V$

### • HDFlash

- Dual voltage
- Cycling:
  - Ⓢ 100 in program memory
  - Ⓢ Emulated Data E<sup>2</sup>prom
- Programming method:
  - Ⓢ Byte per byte or parallel (x256) programming and sectorized erasing with « Embedded Commands »
- Prog/Erase time:
  - Ⓢ See dedicated slide
- Supply conditions
  - Ⓢ  $3.8V \leq V_{DD} \leq 5.5V$  (dedicated low voltage version)
  - Ⓢ  $11.4V \leq V_{PP} \leq 12.6V$



# FLASH PROGRAMMING

- How to program:
  - **ICP:** allows to PROGRAM or REPROGRAM (Xflash and HDFlash devices) the Program Memory when the micro is soldered on the application board or on an EPB socket.
  - **IAP:** allows to program the whole FLASH memory except sector 0, when the application is running



# ST7 IN-APPLICATION PROGRAMMING (IAP)

- In-Application Programming
- Possible with Xflash and HDFlash
- Requirements:
  - Standard application reset sequence
  - Any interface supported by the microcontroller (SPI, USB, CAN...)
  - Always go through a RAM execution to program FLASH parts
- Capabilities:
  - Programming of the whole FLASH memory except sector 0



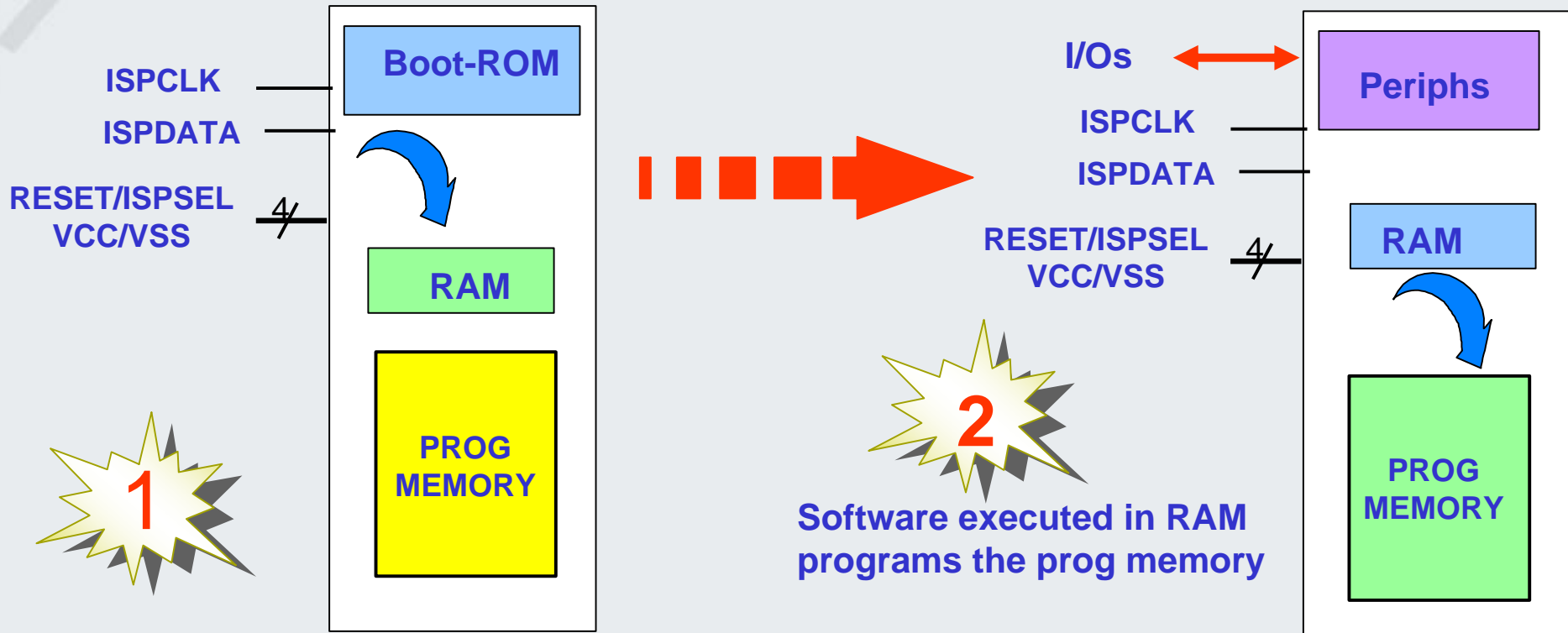
# ST7 IN-SITU PROGRAMING (ISP)

- What is it for ?
  - To PROGRAM or REPROGRAM (flash devices) the Program Memory when the micro is soldered on the application board.
- Main features:
  - Only 6 wires are used (including VDD & VSS).
  - Do not need double voltage on the application board.
  - Supported by ST Visual Programmer (STVP7) tools.
- Performances:
  - ~ 5 s to program 8Kbytes.





# ST7 IN-SITU PROGRAMMING (ISP)



Boot-ROM allows an executable software to be downloaded in RAM through ISPCLK & ISPDATA



Software executed in RAM runs any applicative software with I/Os and peripherals access  
In-Situ Programming uses 6 wires only



# ST7 IN-CIRCUIT PROGRAMING (ICP)

- What is it for ?
  - To PROGRAM or REPROGRAM (flash devices) the Program Memory when the micro is soldered on the application board.
- Main features:
  - Only 4 to 7 wires are used (including VSS and clock depending the configuration).
  - Do not need double voltage on the application board.
  - Supported by the ST Visual Programmer (STVP7) tools.
- Performances:
  - XFlash: 1.3s to program 8Kbytes.
  - HDFlash: 640ms to program 8Kbytes
- ICP versus ISP
  - ICP based on a different protocol called ICC (In-Circuit Communication)
  - ICP more flexible cause the protocol adapts to the slowest part.
  - Flash Programming and ICC Reference Manual available on Internet.



# Xflash Programming Timings with $f_{CPU}=8MHz$

- 1 to 32 Bytes erasing/programming
  - 1~32 byte 5ms
  - 1 kbyte 160ms (// by 32)
- ICC protocol
  - ST7 Receive ~ 20.0 kbyte/s 32byte in ~1.6ms
  - ST7 Transmit ~ 15 kbyte/s 32byte in ~2.2ms
  - the ICC communication can be done during programming therefore masked (receive data+verify)
- Conditions:  $F_{cpu}=8MHz$ , no speed limitation from the programming tool for the communication

|         | Prog.<br>by 32byte blocks + Verify |
|---------|------------------------------------|
| 1kbyte  | 0.16s                              |
| 4kbyte  | 0.64s                              |
| 8kbyte  | 1.28s                              |
| 16kbyte | 2.56s                              |

*Communication timings are proportionnal with  $f_{CPU}$*



# HDFlash Program & Erase Timings with $f_{CPU}=8\text{MHz}$

- Block programming
  - 256 bytes = 12.5ms
  - 32 kbyte ~ 1.6s
  - 60 kbyte ~ 3s
- Byte programming
  - 1 byte ~ 49 $\mu$ s
- VDD=5V and VPP=12V
- Conditions:  $f_{cpu}=8\text{MHz}$ , no speed limitation from the programming tool for the communication
- Sector erasing
  - S0 (4kbyte) 1.5~2s
  - S1 (4kbyte) 1.5~2s
  - S2 (8kbyte) 2~2.50s
  - (24kbyte) 4~4.5s
  - (52kbyte) 8~8.5s
- ICC protocol
  - ST7 Receive ~ 20.0 kbyte/s
  - ST7 Transmit ~ 17.5 kbyte/s
- Verify: CRC (time optimized)

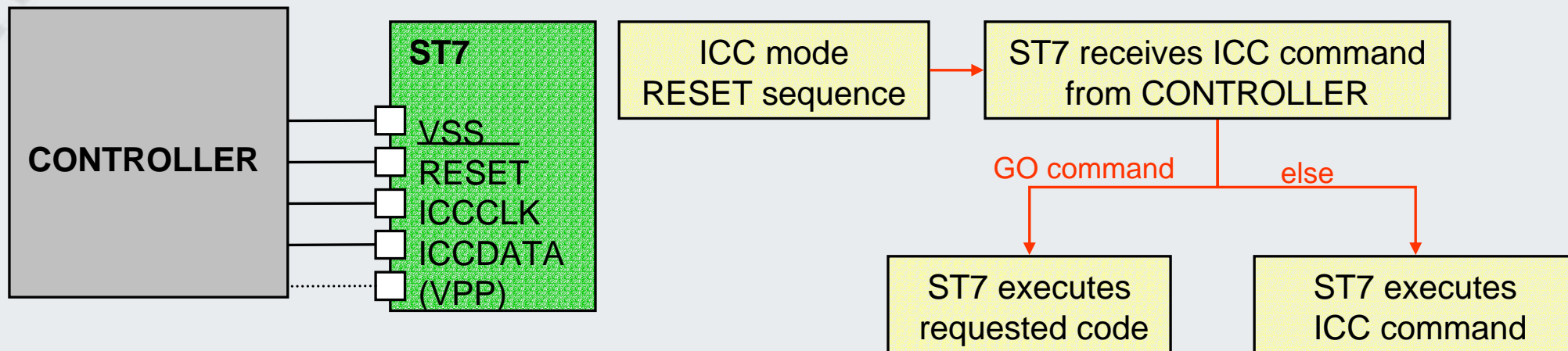
|         | Prog. by 32byte blocks + Verify |          | Erase + Prog + Verify |             |
|---------|---------------------------------|----------|-----------------------|-------------|
|         | Bit Map                         | Checksum | Bit Map               | Checksum    |
| 16kbyte | 2.8s                            | 1.7s     | 7.8s~9.3s             | 6.7s~8.2s   |
| 32kbyte | 5.6s                            | 3.4s     | 12.6s~14.1s           | 10.4s~11.9s |
| 60kbyte | 10.2s                           | 6.3s     | 21.2s~22.7s           | 17.3s~18.8s |



All these timings are proportionnal with  $f_{CPU}$

# ICC MODE

## Communicating with ICC Protocol

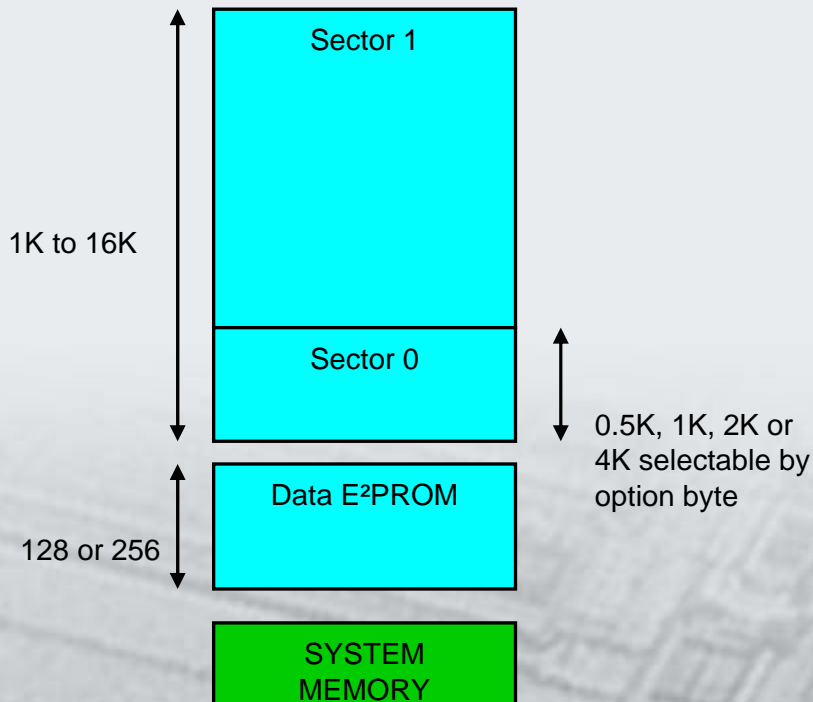


- Dedicated RESET sequence to enter ICC mode
- Real 4 pin ICC protocol
  - ICCCLK, ICCDATA, RESET, VSS (and VPP when needed)
- No speed constraint for ST7 or Controller (PC/Tester)
- Minimum hardware needs to connect to a PC parallel port
- Allow ICD emulation and ICT without any other added external HW resources
- Bidirectionnal communication protocol
- Optimum command base protocol to manage ICP, ICT, ICD
  - Commands: Read, Write, Go, Get SP

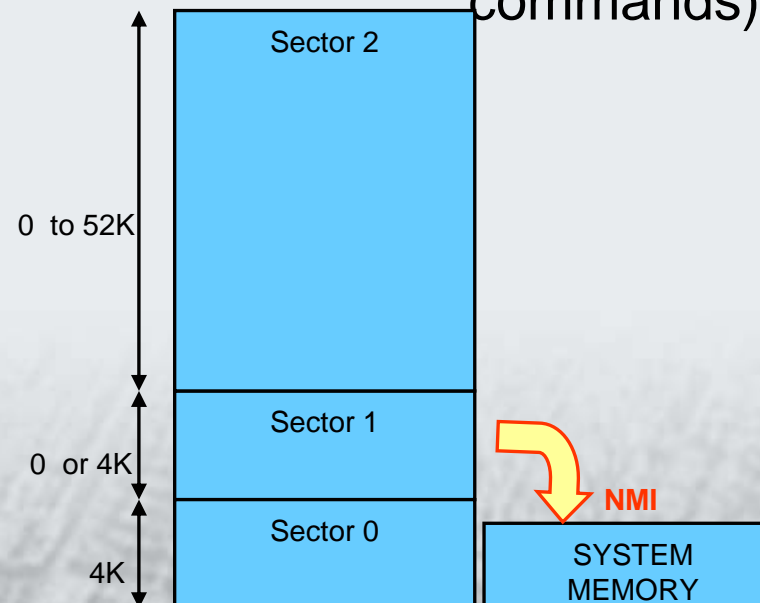


# SYSTEM MEMORY

- Xflash :
  - Location
    - ✓ User space (read accessible by user)
  - Contains
    - ✓ ICC communication routines



- In HDFlash :
  - Location
    - ✓ Paginated (no read accessible by user)
  - Contains
    - ✓ ICC communication routines
    - ✓ « Embedded commands » (Flash programming commands)



# PATENTED MEMORY PROTECTIONS

- **Protection against**



- **Protection strategy**

- Piracy

- READOUT/W protect on Xflash

- Unexpected reprogramming

- RASS (keys)  
(Register Access security System)

- Unexpected trouble occurs during programming

- Write Protected bootloader



# IN-CIRCUIT DEBUGGING (ICD)

- Ability to debug a flash device using the ICC protocol
- Allows low-cost emulator strategy (InDart,...)
- ICD features:
  - Complex data or instructions breakpoints (up to 23 combinations)
  - Abort
  - Step by step
- Two ICD methods:
  - H/W : devices with Debug Module
  - S/W : XFlash without Debug Module (ST7FLITE0)
    - ✓ Limited (less features)
    - ✓ 1 or 2 hundred bytes needed in Flash
    - ✓ No real-time after a stop





# Memory & CPU register Summary

- **How Many CPU registers belong to the ST7 Core?**
  - 6 registers (A, CC, X, Y, PC, SP)
- **Is it possible to place and read data in ROM (program memory)?**
  - Yes, lookup table can be placed in ROM
- **Is it possible to execute code located in RAM ?**
  - Yes, it is used in ISP and ICP modes to program the Program memory
- **Is the Stack handled automatically by the ST7 core ?**
  - Yes, the return address is loaded when a CALL is executed
  - The return address & the CPU registers are saved when the interrupt process is activated



# ST7 INTERRUPTS

## Overview

- Except for the software interrupt (TRAP Instruction), all interrupts can be masked by setting the I BIT in CC
- When an interrupt occurs:
  - The context is saved on the stack (CC, A, X, PC)
  - All other interrupts are masked (the I bit is set By H/W)
  - The interrupt vector is loaded in the Program Counter
- When return from interrupt is executed:
  - The original context is automatically restored (CC, A, X, PC)
  - Interrupts are enabled (I bit reset)
- Priority between interrupts is given by the interrupt address vector (Higher address = higher priority)



# ST7 INTERRUPTS

## ST72254 Interrupt mapping

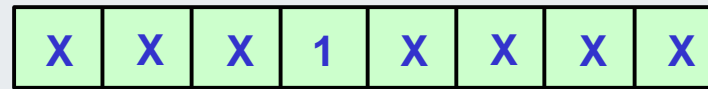
| CPU INTERRUPT        | INTERRUPTS   | REGISTER       | FLAG NAME                           | INTERRUPT SOURCE | VECTOR ADDRESS |
|----------------------|--|----------------|-------------------------------------|------------------|----------------|
| Reset                | Reset  | N/A            | N/A                                 | -                | FFFEh-FFFFh    |
| Trap (instruction)   | Software   | N/A            | N/A                                 | I0               | FFFCh-FFFDh    |
| External Interrupt 0 | Port A   | N/A            | N/A                                 | I1               | FFFAh-FFFBh    |
| External Interrupt 1 | Port B and Port C  | N/A            | N/A                                 | I2               | FFF8h-FFF9h    |
| CSS                  | Clock Filter Interrupt   | CRSR           | CCSD                                | I3               | FFF6h-FFF7h    |
| SPI                  | Transfer Complete<br>Mode Fault  | SPI Status     | SPIF<br>MODF                        | I4               | FFF4h-FFF5h    |
| Timer A              | Input Capture 1<br>Output Compare 1<br>Input Capture 2<br>Output Compare 2<br>Timer Overflow | Timer A Status | ICF1<br>OCF1<br>ICF2<br>OCF2<br>TOF | I5               | FFF2h-FFF3h    |
| Timer B              | Input Capture 1<br>Output Compare 1<br>Input Capture 2<br>Output Compare 2<br>Timer Overflow | Timer B Status | ICF1<br>OCF1<br>ICF2<br>OCF2<br>TOF | I7               | FFEEh-FFEFh    |
| I2C                  | Byte Transfer finished<br>Bus Error<br>STOP Detection  | I2C Status     | BTF<br>BERR<br>SSTOP                | I12              | FFE4h-FFE5h    |



# ST7 INTERRUPTS

## Peripheral Int management

**Periph Status Register**



Interrupt flag set by H/W

**Periph Control Register**



Interrupt Enable bit set by S/W

**Condition Code Register**



Interrupt Mask bit reset/set by S/W



Interrupt generation



**Context switch takes 10 CPU clock cycles**



# ST7 INTERRUPT

## Peripheral Int management

- SOFTWARE EXAMPLE

- **.Main**

```
...  
BSET Control_reg, #IT_enable           ; Enable Periph interrupt  
RIM                                     ; Clear I bit in CC regis  
...                                     ; ie interrupt enabled.
```

- **.Int\_routine**

```
...  
BRES Status_reg, #IT_flag              ; Avoid to process the  
                                         ; same interrupt forever  
IRET                                     ; Return from interrupt  
...
```



# ST7 Interrupt Summary

- Interrupt Vectors:
- Number:
- S/W Priority (Nested mode only):
- Interrupt Reaction Time:
- Automatic register pushed:
- up 16 Vectors
- 16 levels hardwired
- 4 levels user configurable
- 1.250 $\mu$ s to 2.750  $\mu$ s (end of the current instruction +10 cpu cycles)
- Program counter, accumulator, CC, X

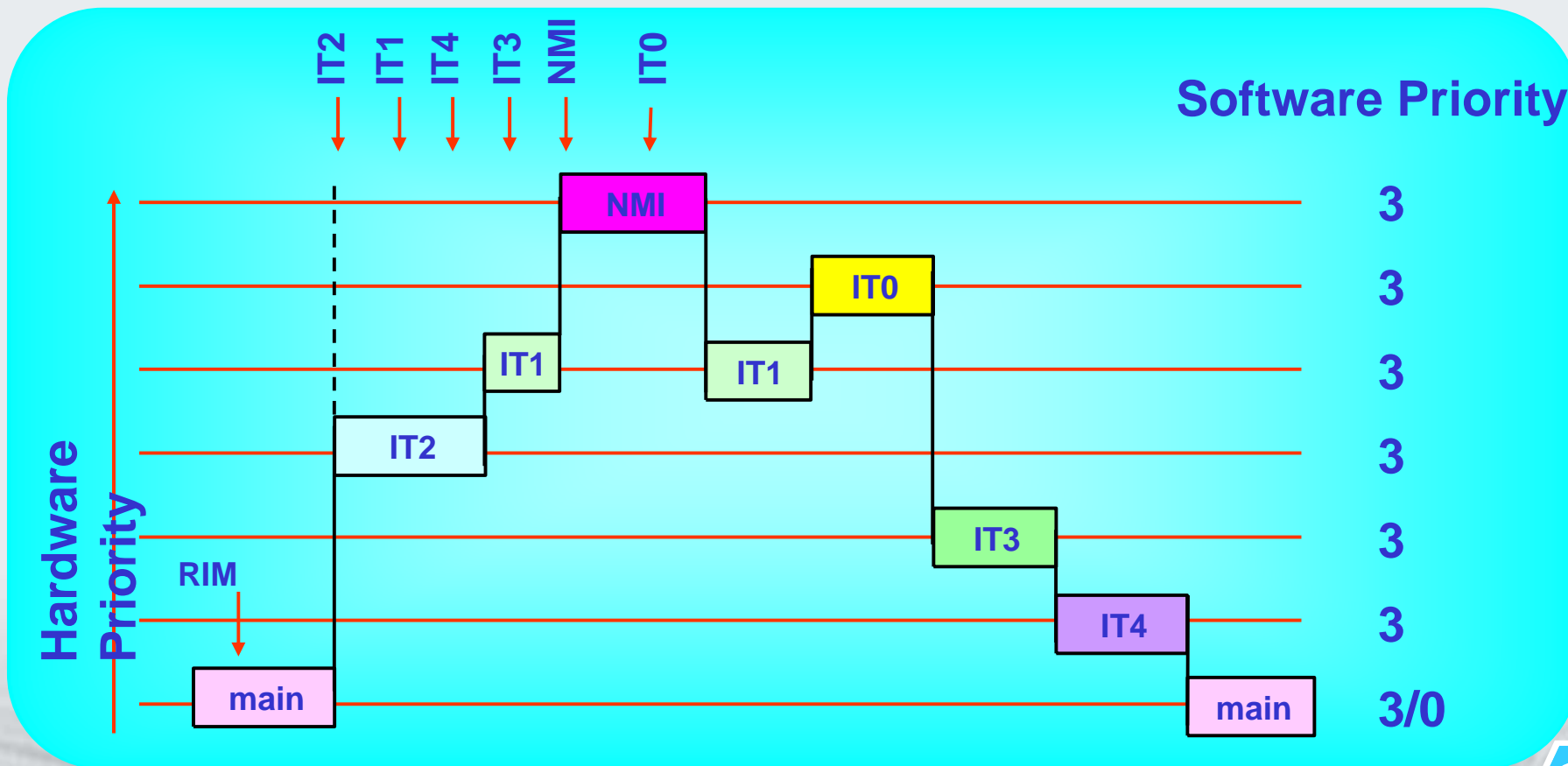


**Software levels allows the ST7 nested interrupt process (availability of nested interrupt feature is device dependant)  
At least one Interrupt Vector per Peripheral**



# Concurrent Interrupt Management

- An interrupt can not be interrupted by another one
- Except by the NMI (Non Maskable Interrupt) or TLI (Top level interrupt)



# Nested Interrupt

- The 4 interrupt S/W levels are set thanks to the pair of bits I0, I1.

| Interrupt Software Priority  | Level | I1 | I0 |
|------------------------------|-------|----|----|
| Level 0 (main)               | Low   | 1  | 0  |
| Level 1                      |       | 0  | 1  |
| Level 2                      |       | 0  | 0  |
| Level 3 (=interrupt disable) | High  | 1  | 1  |

to be compatible  
with previous bit I

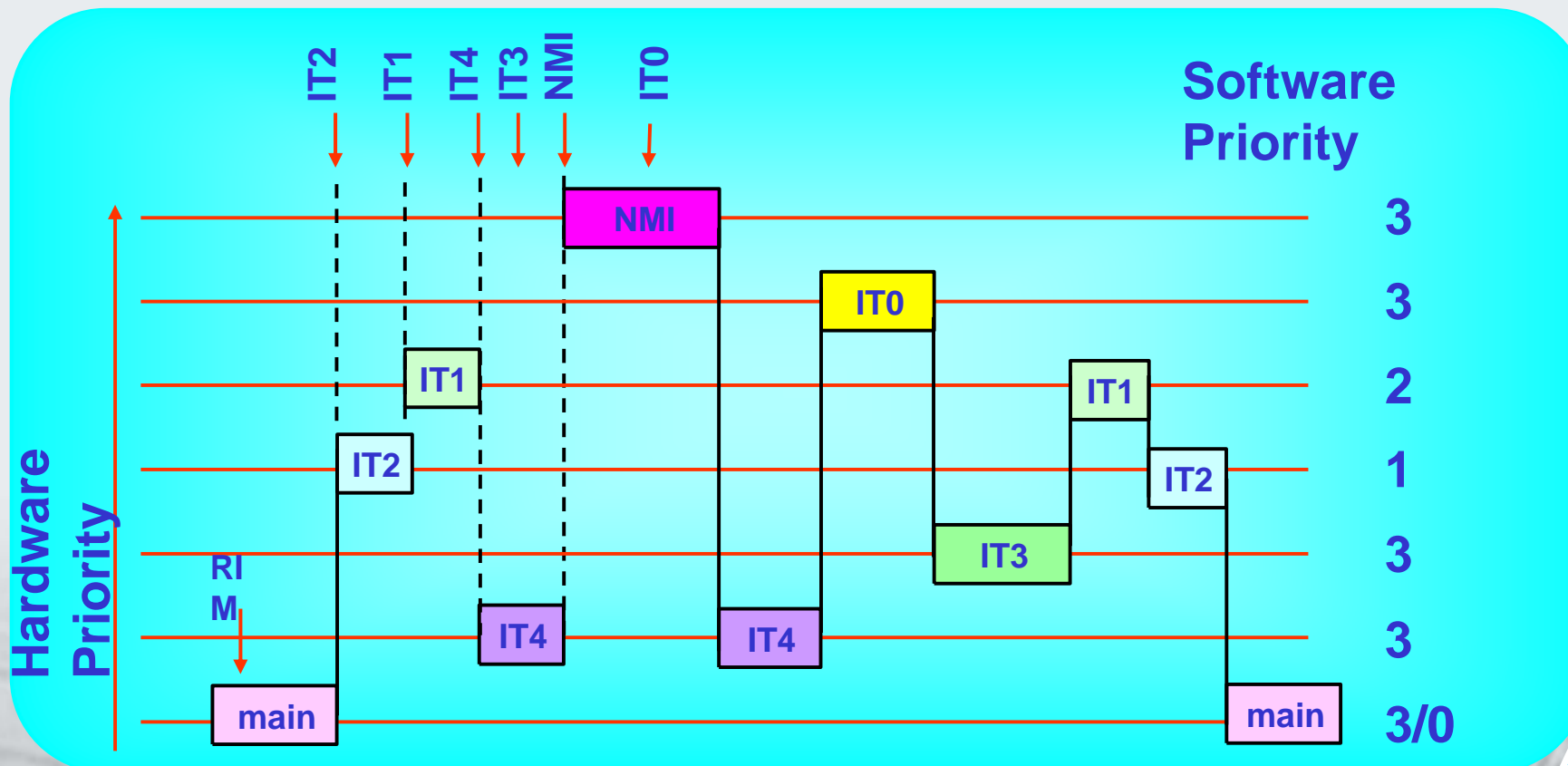
- 1 pair of bits by interrupt vector stored in the ISPR registers
- The pair of bits is copied in the CC register when the corresponding IT is activated (software level greater than the current one).





# Nested Interrupt Management

- An interrupt can be interrupted by:
  - The NMI (Non Maskable Interrupt) or TLI (Top Level Interrupt)
  - An interrupt request having an higher software Priority



# Interrupts Summary

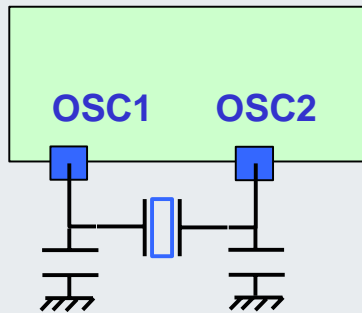
- **How many interrupt vectors can be used in the ST7 ?**
  - Up to 16, at least one per peripheral.
- **Are the software interrupt levels able to be modified during the application?**
  - Yes, in that case the interrupt routines priority can be modified during the program execution
- **What are the instructions that enable & disable the Interrupts?**
  - RIM: Reset Interrupt Mask (I bit =0, allows the interrupts)
  - SIM: Set interrupt Mask (I bit =1, disable the interrupts)



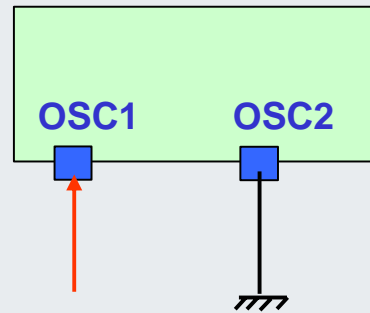


# Multi oscillator (1)

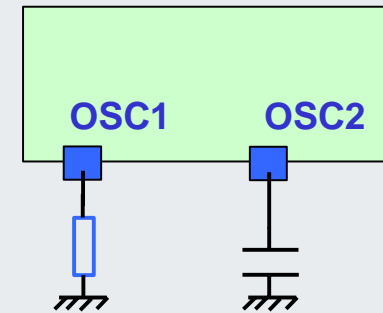
- Advanced ST7 clock system



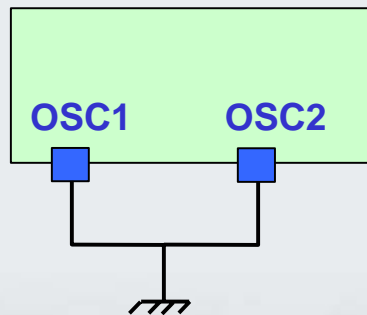
• QUARTZ/CERAMIC



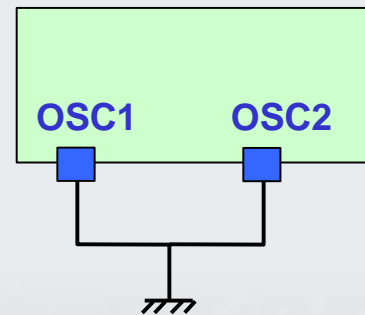
• EXTERNAL SOURCE



• EXTERNAL RC



• INTERNAL # 4Mhz



• 1% ACCURACY  
INTERNAL RC

- + Low frequency backup safety oscillator (option byte)



# Multi Oscillator (2)

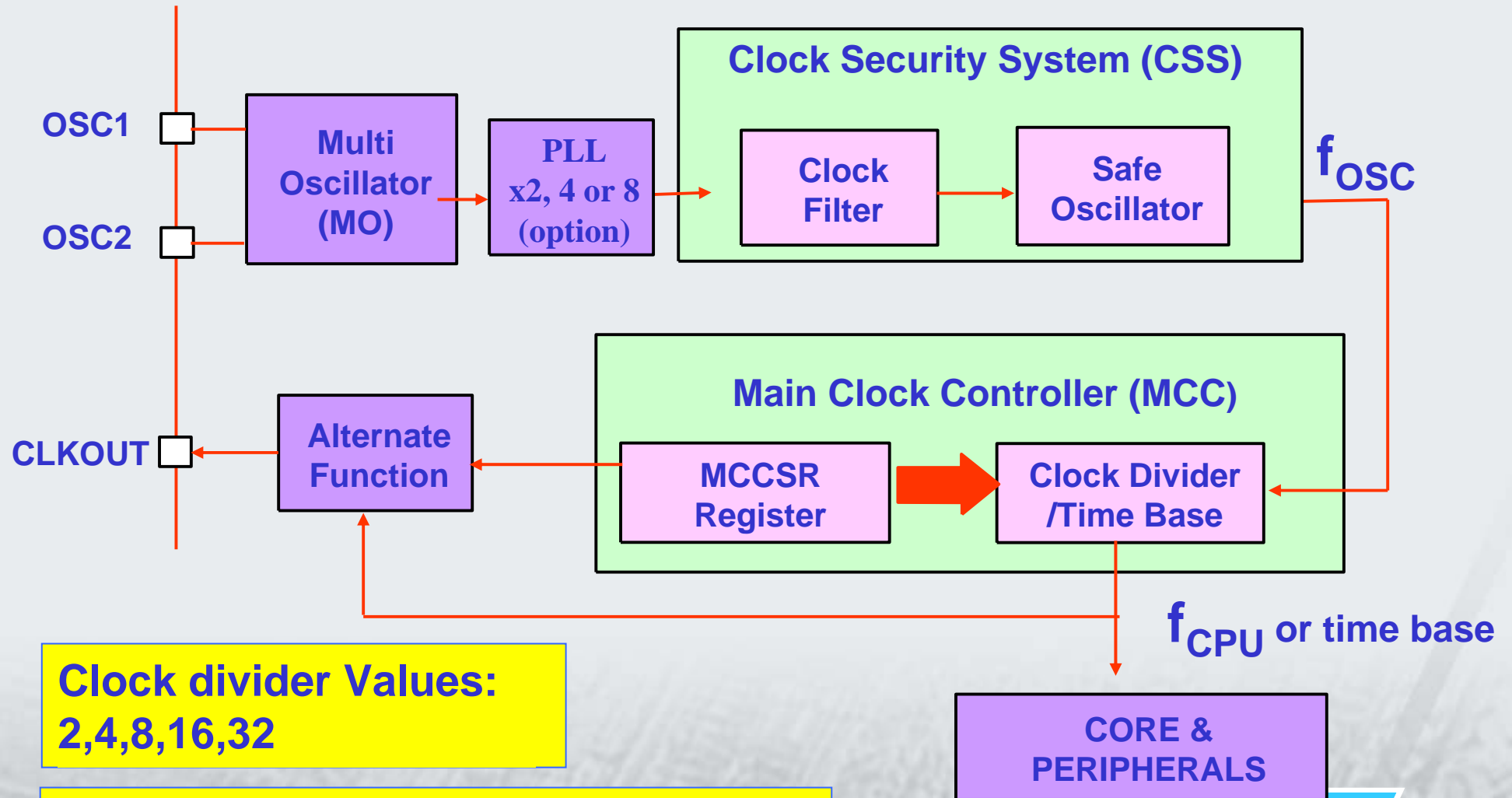
- 4 Crystal/Ceramic Oscillators
  - Designed to reduce EMI & consumption
    - ✓ Low speed
    - ✓ Mid low speed
    - ✓ Mid high speed
    - ✓ High speed
- 1 External RC Oscillator
- 1 Internal RC Oscillator
- 1 Internal Safe Oscillator
- Frequency range:
  - ✓ 1 to 2 MHz
  - ✓ 2 to 4 MHz
  - ✓ 4 to 8 MHz
  - ✓ 8 to 16 MHz
- 1 to 14 MHz
- # 1 to 8 MHz
- # 250KHz and #3MHz for new products (Xflash and HDFlash)

Oscillator selected by option byte





# Main Clock Controller



**Clock divider Values:  
2,4,8,16,32**

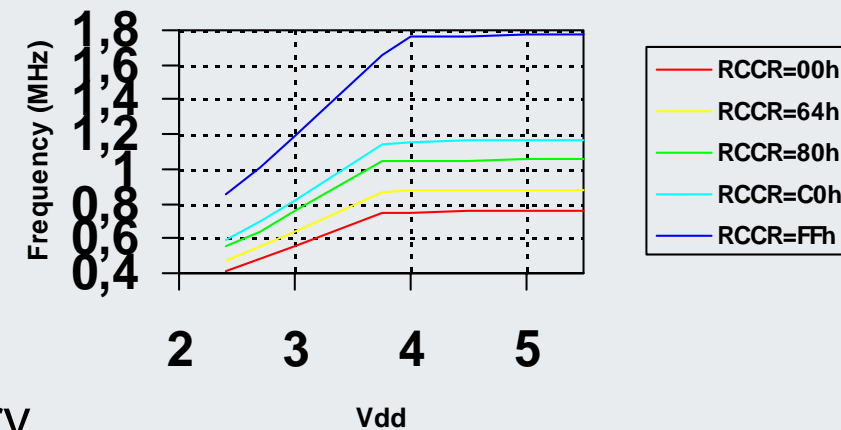
**Time Base Prescaler (Active Halt):  
32000,64000,160000,400000**



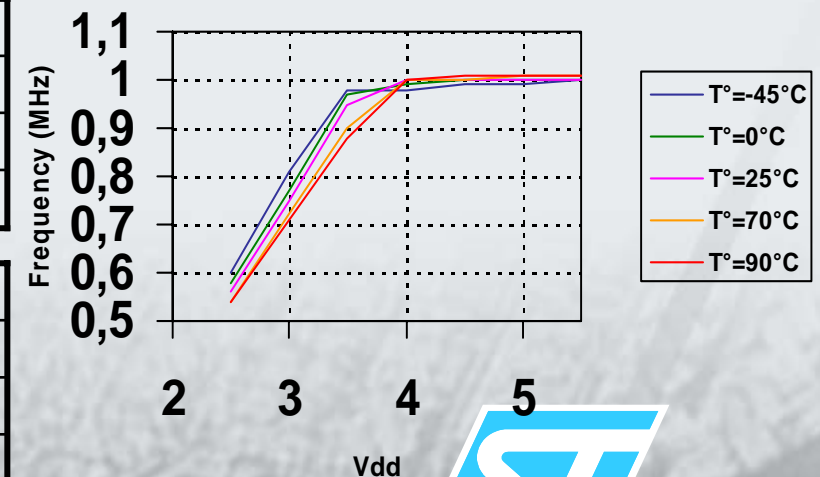
# RC1% Architecture

- Calibration used for process, temperature and voltage derive compensation
- Expected frequency & accuracy obtained by SW tuning and by loading RCCR register after each reset
  - LD A, \$1000h
  - LD RCCR, A
- Predefined RCCRx values stored in memory after calibration during ST test flow

Typical internal RC freq vs RCCR values @ 25°C



Typical internal RC freq with RCCR=RCCR0



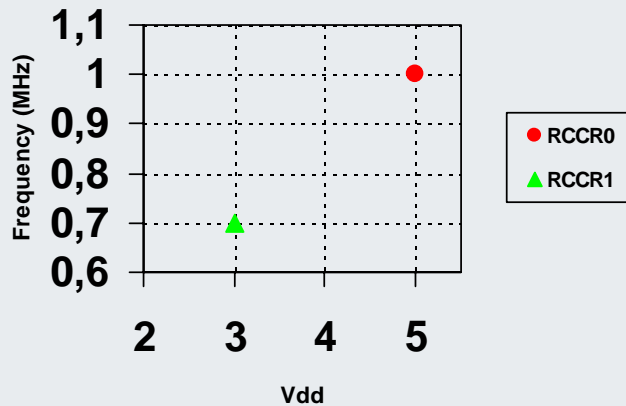
| RC accuracy with RCCR=RCCR0<br>1MHz<br>5V Range | Conditions                | Min   | Typ     | Max  |
|---|---------------------------|-------|---------|------|
|   | T°=25°C, Vdd=5V           | -0.5% | +/-0.2% | 0.5% |
|   | T°=25°C, Vdd=4.5V to 5.5V | -1%   |         | +1%  |
|   | T°=-40°C to 85°C, Vdd=5V  | -2%   |         | +1%  |

| RC accuracy with RCCR=RCCR1<br>700KHz or 1MHz<br>3V Range | Conditions                | Min  | Typ     | Max  |
|---|---------------------------|------|---------|------|
|   | T°=25°C, Vdd=3V           | -2%  | +/-0.5% | 2%   |
|   | T°=25°C, Vdd=2.7V to 3.3V | -20% |         | +20% |
|   | T°=-40°C to 85°C, Vdd=3V  | -5%  |         | +10% |

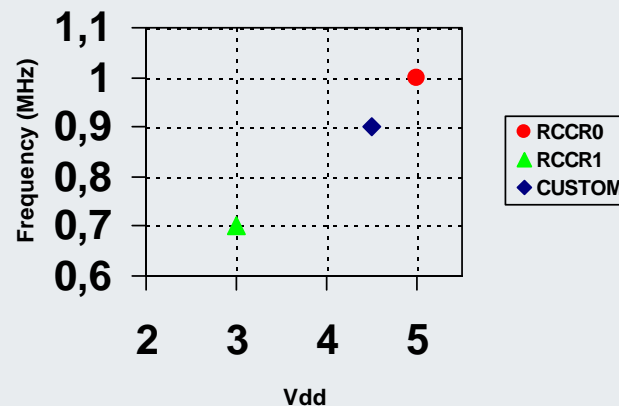


# When can RC calibration data be stored in non volatile memory

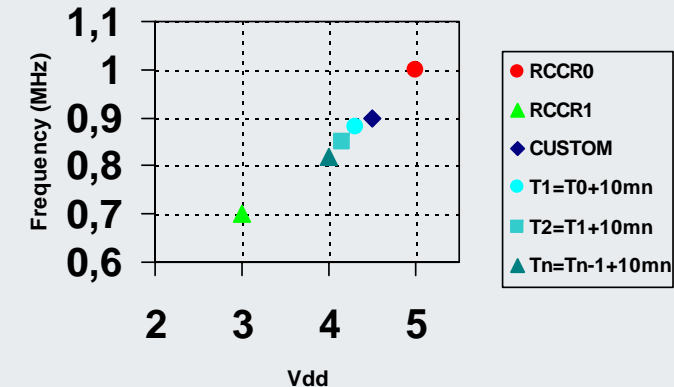
Predifined calibration values



Customer calibration value



Application exemple with new calibartion each 10 minutes



## ST FACTORY

2 PREDIFINED CALIBRATION VALUES FOR EACH PART

- **CONDITIONS :**
  - RCCR0 : 1MHz @ 5V @ 25°C
  - RCCR1 :
    - ✓ 0.7MHz @ 3V @ 25°C (for Lite0 and 2)
    - ✓ 1MHz @ 3V @ 25°C (for Lite3, 1B, Ultra ...)

## CUSTOMER FACTORY

CALIBRATE AND DEDICATE TO THE APPLICATION

- **CONDITIONS : (OPTIONAL)**
  - FREQ @ VDD @ T° CUSTOMER CHOICE FOR BEST APPLICATION FITTING

## IN APPLICATION

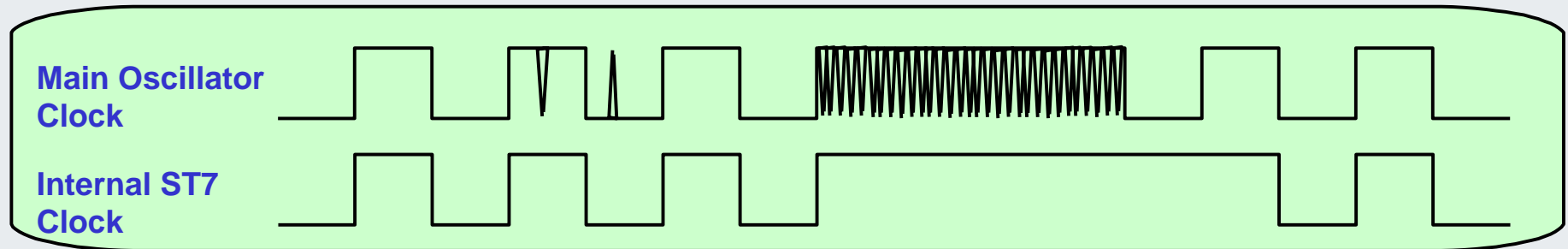
CALIBRATE FOR SPECIFIC CONDITIONS ADAPTATION

- **CONDITIONS : (OPTIONAL)**
  - FREQ @ VDD @ T° APPLICATION DEPENDANT
  - SOFTWARE ROUTINE CUSTOMIZED
  - REAL TIME BASE NEEDED (EX : AN1324, CALIBRATION WITH 50/60Hz MAINS)

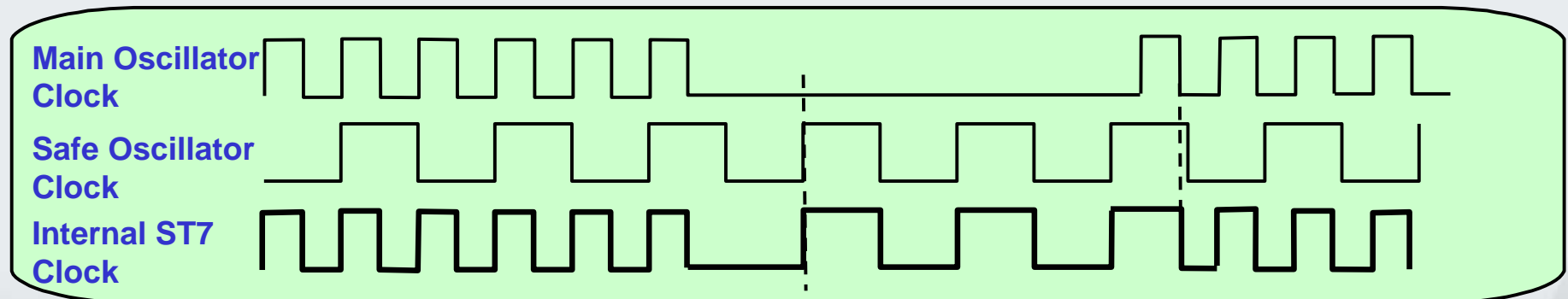


# Clock Security System

- Clock Filter Function



- Safe Oscillator



**CSSD bit is set by H/W if one of the safety function is activated and can generate a maskable interrupt request**





# Clock Source Capability

|                         | FLITE0 | FLITE2 | F344 | F324 | F521 | F561 |
|-------------------------|--------|--------|------|------|------|------|
| QUARTZ/<br>CERAMIC      |        | X      | X    | X    | X    | X    |
| EXTERNAL<br>CLOCK       | X      | X      | X    | X    | X    | X    |
| EXTERNAL<br>RC          |        |        | X    | X    | X    | X    |
| INTERNAL<br>RC          |        |        |      | X    | X    | X    |
| 1%<br>INTERNAL<br>RC    | X      | X      | X    |      |      |      |
| LOW POWER<br>RC FOR AWU |        | X      | X    |      |      | X    |



# ST7 CORE

## Reset sources

- External reset using reset pin
  - Purpose: allow to generate an external reset
  - Condition: reset pin pull low
- Power supply dependent reset using LVD
  - Purpose: ensure the MCU is in a known state whatever Vcc
  - Condition: internal reset when Vcc reaches Vcc min
- Watchdog reset using the watchdog timer
  - Purpose: guarantee the safety in case of software trouble
  - Condition: internal reset when the WD register is not refreshed
- Illegal opcode
  - Purpose: guarantee the safety in case of software trouble
  - Condition: internal reset when executing an undefined prebyte or opcode





# ST7 ENHANCED RESET SYSTEM

- 4 Reset sources
  - Watchdog
  - Low Voltage Detection (LVD)
  - External RESET pin
  - Illegal opcode
- Complete reset management
  - Flags on Reset sources
  - Internal Reset externally issued to reset the whole application

## COMPLETE RESET SEQUENCE

Phase with  
RESET pin  
grounded

Internal Reset  
4096 or 256 CPU clock  
cycles

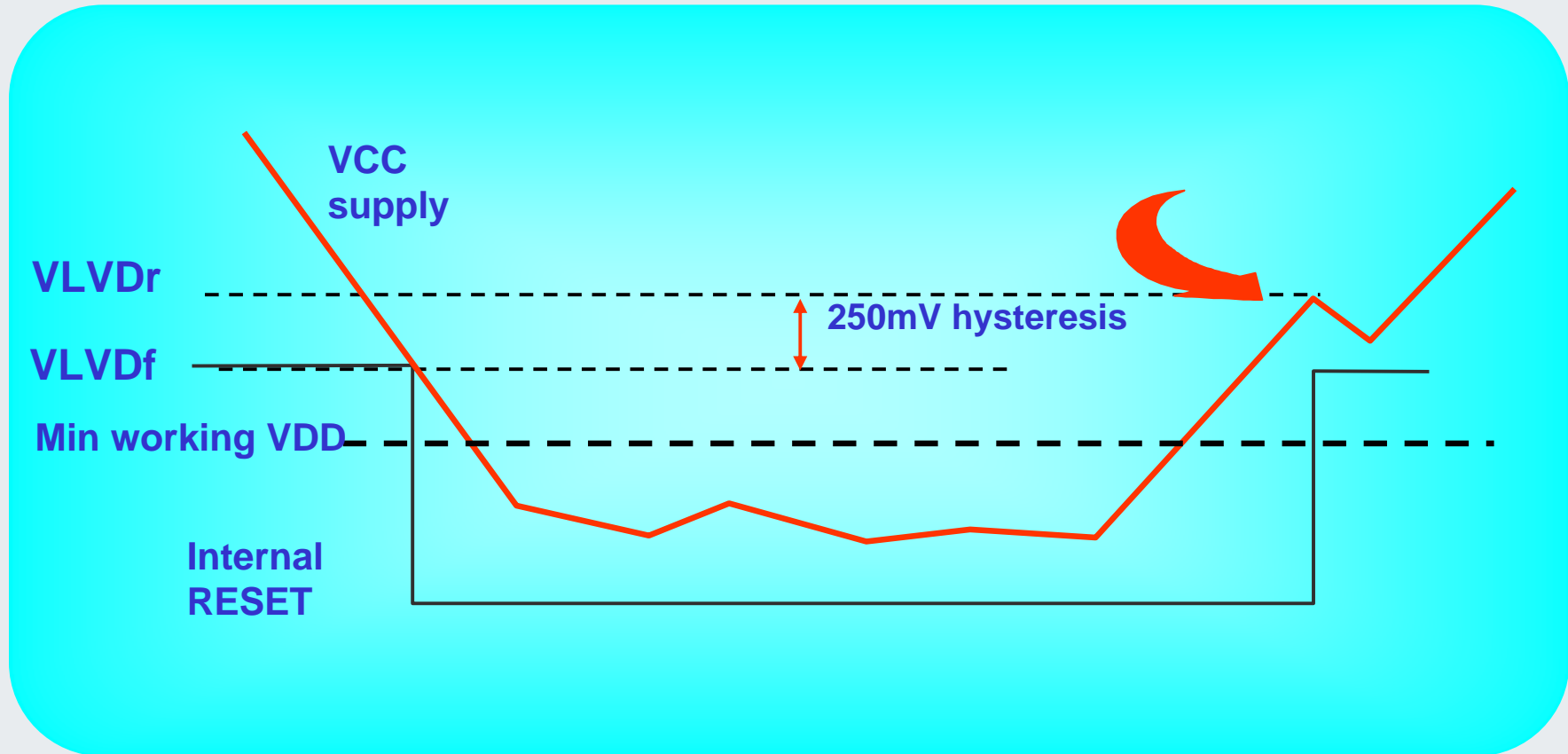
Fetch Reset  
Vector

256 in the case of the clock is provided by the  
internal RC or by the CLKIN  
4096 in the case of a resonator on OSC1/OSC2

From internal Watchdog Reset or Illegal Opcode: Phase # 30µs  
From internal LVD Reset: 30µs < Phase < Low voltage duration  
From external RESET pin: 30µs < Phase < Ext RESET pulse width



# ST7 LVD GENERATION



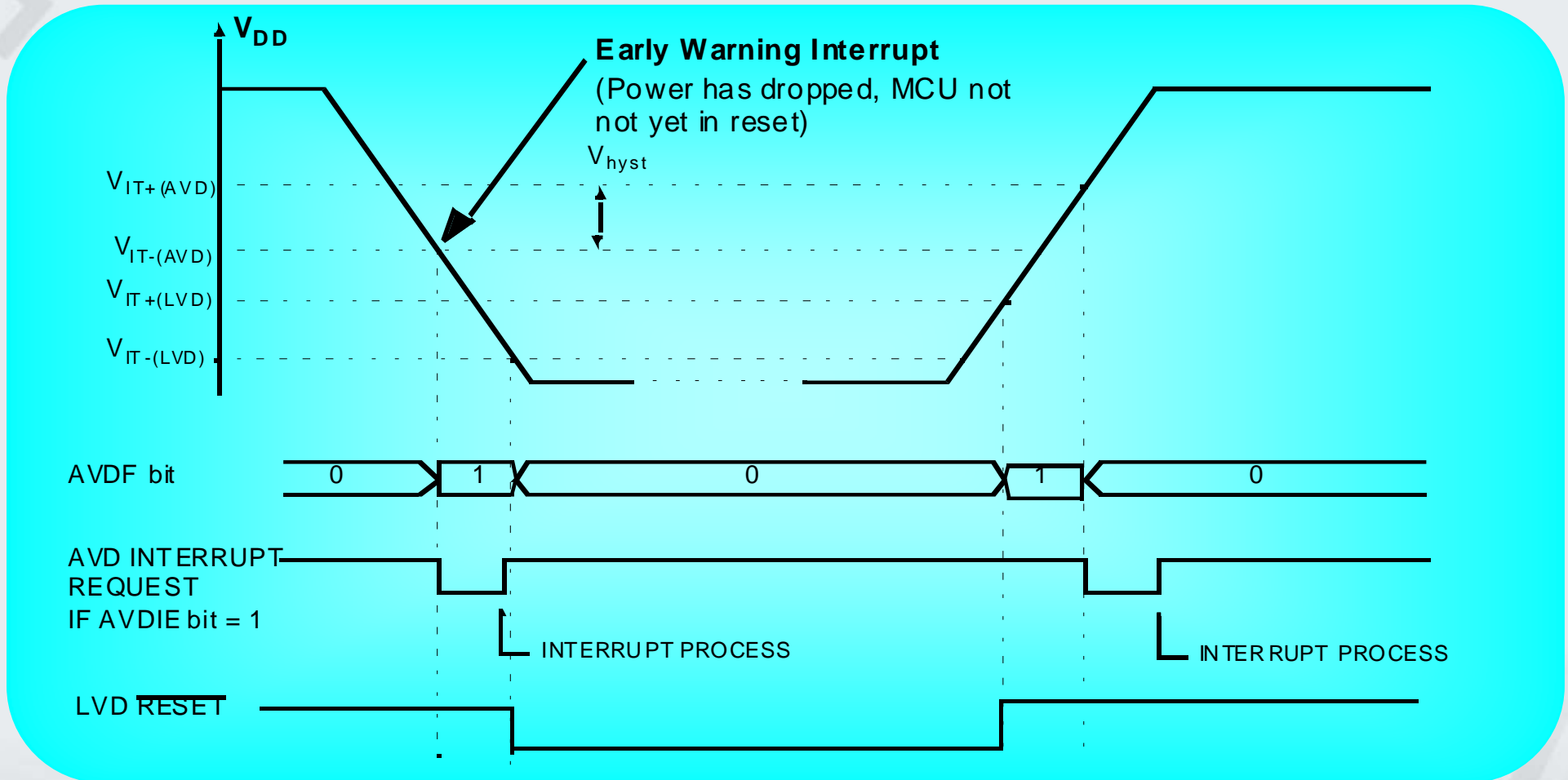
- 3 Selectable levels

- Activation Flag

- RESET pin tied to GND



# ST7 LVD/AVD GENERATION



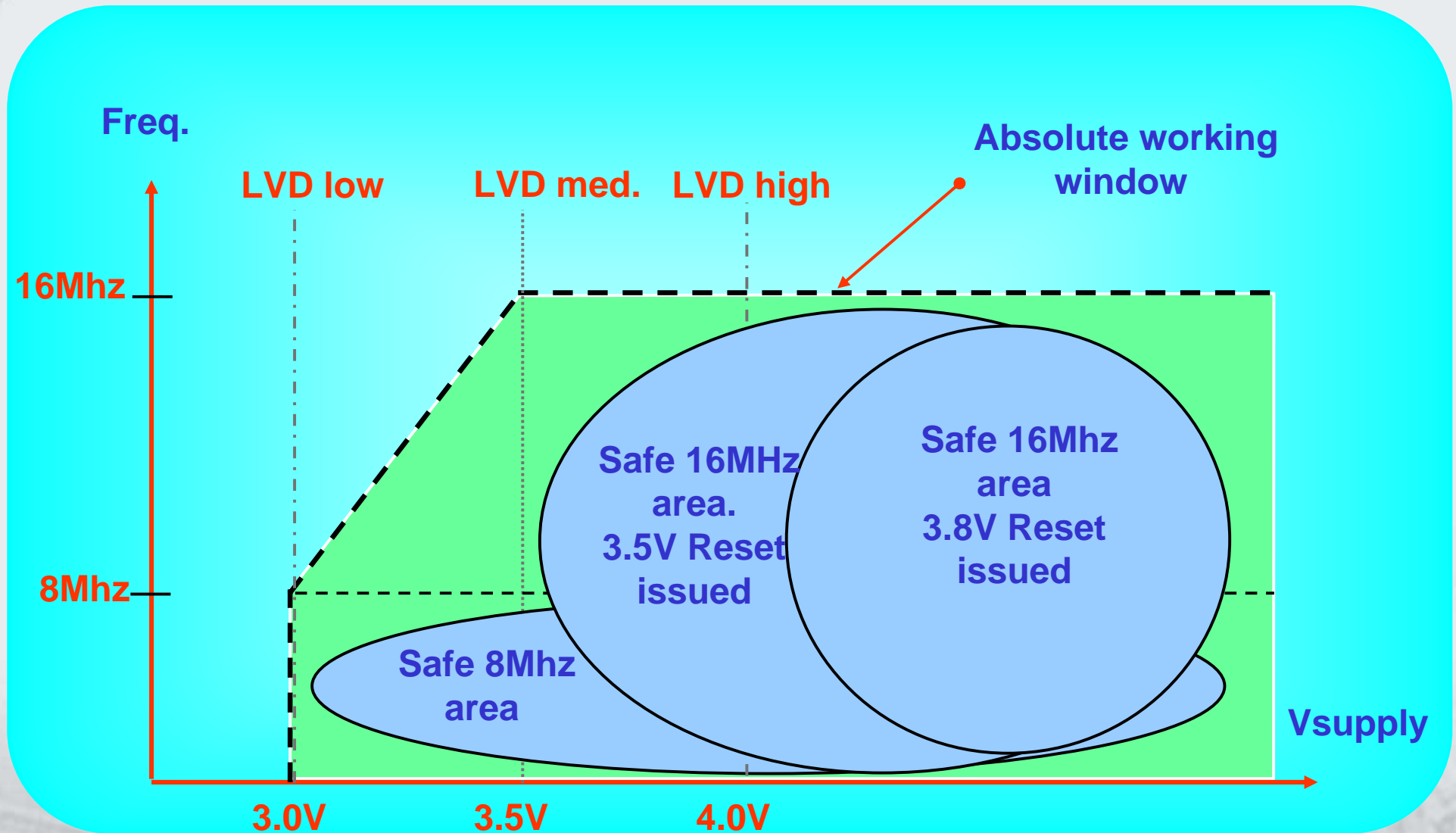
- 3 Selectable levels

- Activation Flag

- RESET pin tied to GND



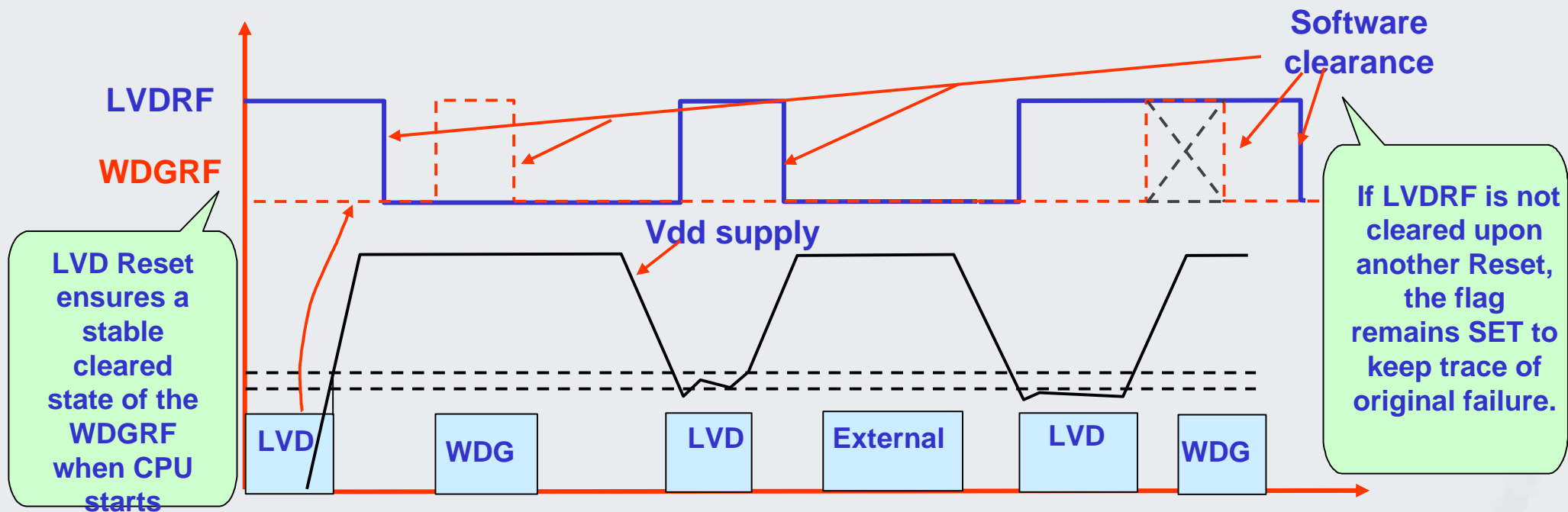
# 3 LVD LEVELS TO OPTIMIZE THE SAFE AREA



LVD/AVD levels are device dependant



# LVD PART OF COMPLETE RESET MANAGEMENT



| Original RESET source  | LVDRF | WDGRF |
|------------------------|-------|-------|
| External RESET pin     | 0     | 0     |
| Watchdog Reset Flag    | 0     | 1     |
| Low Voltage Reset Flag | 1     | X     |

# ST7 WATCHDOG

## Overview (1)

- Its purpose is to detect the occurrence of a software fault. It must be regularly refreshed by the program:
  - LD           A,#\$FF
  - LD           WDGCR, A   ; Reload WD
- 2 different watchdogs can be selected by option bit:
  - Hardware Watchdog:
    - ✓ WD automatically activated upon reset
  - Software Watchdog:
    - ✓ It is activated by software (bit 7 = 1). Once activated, it cannot be disabled







# ST7 WATCHDOG

## Overview (2)

- Reset and watchdog:
  - HALT instruction can generate a reset if watchdog is activated and if the option byte allows it
  - The Watchdog can be used to generate a software reset
    - ✓ (bit 7 = 1, bit 6 = 0) WDGCR = \$80 ; Reset !
- Difference between the Lite family and the other ST7
  - On Lite, the watchdog period is  $X \times 16000 T_{cpu}$  with X between 1 and 3Fh
  - On ST7, the watchdog period varies between :

Min : WDGCR = C0h

$$\begin{aligned}\Delta &= 2^0 \times 12288 = 12288 \text{ clock cycles} \\ &= 1.54 \text{ ms for } F_{cpu} = 8\text{MHz}\end{aligned}$$

Max : WDGCR = FFh

$$\begin{aligned}\Delta &= 2^6 \times 12288 = 786432 \text{ clock cycles} \\ &= 98.30 \text{ ms for } F_{cpu} = 8\text{MHz}\end{aligned}$$

**For XFlash and HDFlash:**

**Special formula are given in the datasheets**



# Clock & Reset system Summary

- **What are the maximum oscillator frequency and the maximum CPU frequency ?**
  - $f_{osc} = 16\text{MHz}$  &  $f_{CPU} = 8\text{ MHz}$  in run mode.
- **How many internal RC oscillator are implemented on ST7 ?**
  - 2, the first one running at 1 to 8 MHz and the backup safety oscillator.
- **What are the internal reset sources?**
  - LVD, Watchdog, Illegal opcode.
- **Can these internal resets be detected externally?**
  - Yes, thanks to the reset pin that acts as an input/output pin.



# ST7 CLOCK IN LOW POWER MODES

- **RUN MODE:**  $F_{cpu} = F_{osc} / 2$ 
  - Core & periph. running except if WAIT (Core stopped) selected
- **SLOW MODE:** Division ratio from 4 to 32 by software
  - Core & periph. running except if WAIT (Core stopped) selected
- **ACTIVE HALT:** Division ratio from 32000 to 400000 by software
  - Core & periph. stopped but periodic wake-up through interrupts
- **AUTO WAKE UP :** Based on a low power internal RC allowing a periodic wake up
- **HALT MODE:** Oscillator stopped
  - Core & periph. stopped



# ST7 LOW CONSUMPTION MODES

## Overview

- Typical ST7 consumption:
  - HDFlash : 7 mA with  $f_{osc} = 16$  MHz and  $VDD = 5V$
  - XFlash : 5 mA with  $f_{osc} = 16$  MHz and  $VDD = 5V$
- To reach lowest power consumption
  - Switch off unused peripherals
  - Configure I/Os as output low level and connect them to GND
  - Use the lowest oscillator frequency possible
  - Use the Slow mode, Wait mode or better the Halt mode



# ST7 LOW CONSUMPTION MODES

## Slow mode

- Goal: reduce the consumption by reducing the clock speed keeping the same Oscillator frequency
- Enter by: configuring the miscellaneous register
- Causes: the CPU clock slows down
  - The  $f_{osc}$  can be divided by 4, 8, 16 or 32 rather than 2, or only 32 for small products
- Exit by: configuring the miscellaneous register



# ST7 LOW CONSUMPTION MODES

## Wait mode

- Goal: Reduce the consumption while monitoring external events
- Enter by: execution of the Wait For Interrupt instruction (WFI)
- Causes: the micro is software frozen
  - Program execution stopped
  - Memory and registers remain unchanged
  - The oscillator still provides a clock to the peripherals
- Exit by
  - Reset (Watchdog, reset pin)
  - Internal interrupts (timer A, timer B, A/D, SPI etc)
  - External interrupts (I/O ports)



# ST7 LOW CONSUMPTION MODES

## Active Halt mode

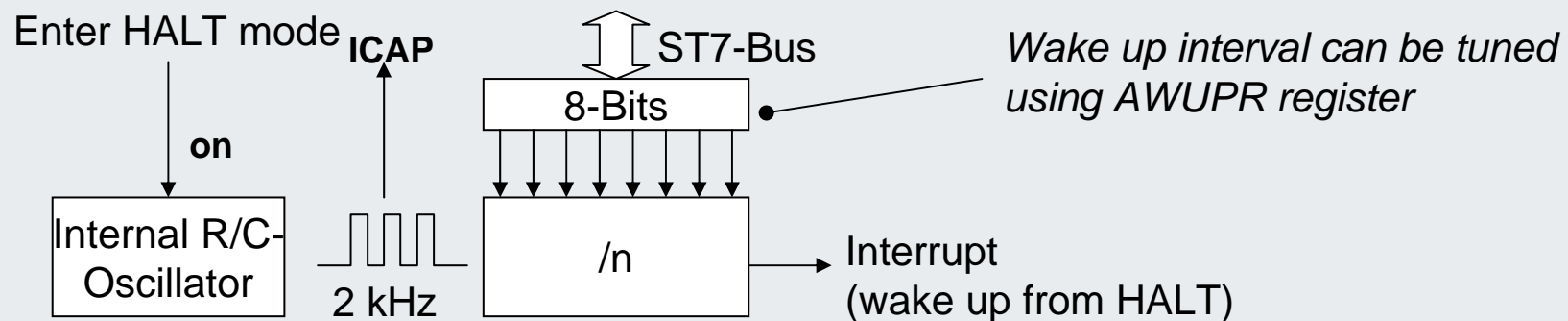
- Goal: Reduce the consumption to the lowest value while monitoring a real time clock.
- Enter by: execution of the HALT instruction while the OIE (Oscillator Interrupt Enable) bit is set.
- Causes: the micro is SW frozen, all the peripherals are stopped, only the Oscillator & the Main Oscillator Counter are running.
- Exit by
  - External Reset
  - Interrupts with exit from halt capability (External IT,..)
  - Time Base Interrupt (32000,64000,160000,400000 \*T<sub>CPU</sub>)
  - From 2ms to 25ms with f<sub>OSC</sub>=16MHZ



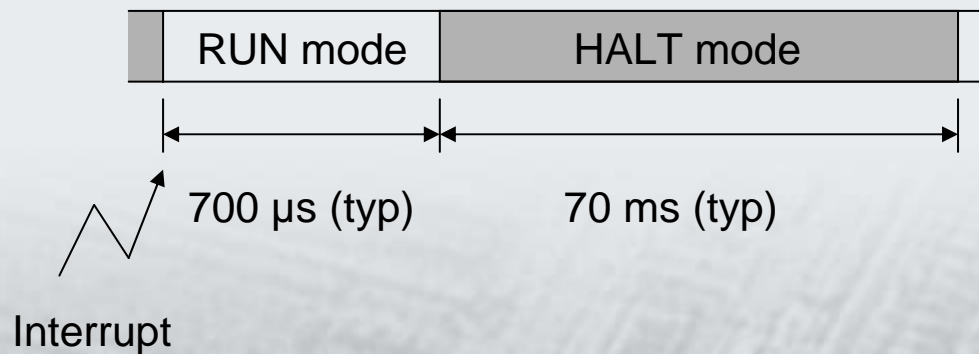
# Auto wake up mode

i.e. cyclic wakeup every 70 ms with total conso < 50 $\mu$ A

- **Basic Principle**  
**Based on internal RC-oscillator (low power)**



- **Power Consumption**



- **Low system power consumption**  
<50 $\mu$ A in total in this mode  
(application dependent)
- **Fast startup after 256 cycles possible**  
around 30 $\mu$ s @  
8MHz internal





# ST7 LOW CONSUMPTION MODES

## Halt mode

- Goal: Reduce the consumption to the lowest value
- Enter by: execution of the HALT instruction
- Causes: the micro is SW and HW frozen
  - Program execution stopped
  - Memory and registers remain unchanged
  - The oscillator stopped
- Exit by
  - External Reset
  - External interrupts (I/O ports)



# TYPICAL CONSUMPTIONS

- During wait mode or HALT MODE, BIT I (INTERRUPT BIT) of CC Register is automatically reset to enable interrupt
- Typical consumptions at  $V_{dd}=5V$ ,  $F_{cpu}=8MHz$ :  
Auto wake up  $\sim 30\mu A$  for the ST72F561, FLITE2  
Active Halt  $\sim 50\mu A$  + oscillator consumption

|                       | <b>ST7FLITE0</b> | <b>ST72F264</b> | <b>ST72F324</b> | <b>ST72F521</b> |
|-----------------------|------------------|-----------------|-----------------|-----------------|
| <b>RUN</b>            | 4.5mA            | 7.2mA           | 7.1mA           | 7.1mA           |
| <b>SLOW<br/>(/32)</b> | 0.75mA           | 0.7mA           | 1.1mA           | 1.1mA           |
| <b>WAIT</b>           | 1.75mA           | 3.6mA           | 3.5mA           | 4.5mA           |
| <b>HALT</b>           | $<1\mu A$        | $<1\mu A$       | $<1\mu A$       | $<1\mu A$       |



# PROGRAMMING TIPS

## Low Consumption Modes

- After exiting from halt mode or wait mode after reset, the micro waits 256 or 4096 CPU clock cycle (STABILIZATION TIME) before being operational (clock source dependant)
- Source that allows to exit from WFI Or halt mode
  - Internal Interrupts => Wait and Halt modes
  - External Interrupts => Halt mode
- During wait mode or HALT MODE, BIT I (INTERRUPT BIT) of CC Register is automatically reset to enable interrupt

